On the Existence of ϕ -Recurrent $(LCS)_n$ -Manifolds

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Abstract: The object of the present paper is to provide the existence of ϕ -recurrent $(LCS)_n$ -manifolds with several non-trivial examples.

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1. Introduction

Recently the first author ([1]) introduced the notion of Lorentzian concircular structure manifolds (briefly $(LCS)_n$ -manifolds) with an example, which generalizes the notion of LP-Sasakian manifolds introduced by Matsumoto ([4]). The notion of local symmetry of a Riemannian manifold has been weakened by many authors in several ways to a different extent. As a weaker version of local symmetry, T. Takahashi ([5]) introduced the notion of local ϕ -symmetry on a Sasakian manifold.

In the context of Lorentzian geometry, the notion of local ϕ -symmetry is introduced and studied by Shaikh and Baishya ([2]) with several examples. Generalizing these notions, in the present paper we introduce the notion of locally ϕ -recurrent $(LCS)_n$ -manifolds. Section 2 is concerned with some curvature properties of $(LCS)_n$ -manifolds. Section 3 consists of locally ϕ -recurrent $(LCS)_n$ -manifolds and obtained a necessary and sufficient condition for such a manifold to be of locally ϕ -recurrent. It is shown that in a locally ϕ -recurrent $(LCS)_n$ -manifold, $\frac{r}{2}$ is an eigenvalue of the Ricci tensor corresponding to the eigenvector associated to the 1-form of the recurrence, r being the scalar curvature of the manifold. And also in a locally ϕ -recurrent $(LCS)_n$ -manifold, the recurrent vector field is obtained as $\rho = \frac{1}{r} \operatorname{grad} r$. Finally, the existence of such a manifold is ensured by several non-trivial examples in both odd and even dimension.

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2.
$$(LCS)_n$$
-Manifolds

An n-dimensional Lorentzian manifold M is a smooth connected paracompact Hausdorff manifold with a Lorentzian metric g, that is, M admits a smooth symmetric tensor field g of type (0,2) such that for each point $p \in M$, the tensor $g_p: T_pM \times T_pM \to \mathbb{R}$ is a non-degenerate inner product of signature $(-,+,\ldots,+)$, where T_pM denotes the tangent vector space of M at p and \mathbb{R} is the real number space. A non-zero vector $v \in T_pM$ is said to be timelike (resp., non-spacelike, null, spacelike) if it satisfies $g_p(v,v) < 0$ (resp., $\leq 0, = 0, > 0$) ([3]).

DEFINITION 2.1. In a Lorentzian manifold (M,g) a vector field P defined by

$$g(X, P) = A(X)$$

for any $X \in \chi(M)$ is said to be a concircular vector field if

$$(\nabla_X A)(Y) = \alpha \{ g(X, Y) + \omega(X) A(Y) \}$$

where α is a non-zero scalar and ω is a closed 1-form.

Let M^n be a Lorentzian manifold admitting a unit timelike concircular vector field ξ , called the generator of the manifold. Then we have

$$g(\xi, \xi) = -1. \tag{2.1}$$

Since ξ is a unit concircular vector field, it follows that there exists a non-zero 1-form η such that for

$$g(X,\xi) = \eta(X), \qquad (2.2)$$

the equation of the following form holds

$$(\nabla_X \eta)(Y) = \alpha \{ g(X, Y) + \eta(X)\eta(Y) \} \quad (\alpha \neq 0)$$
 (2.3)

for all vector fields X, Y where ∇ denotes the operator of covariant differentiation with respect to the Lorentzian metric g and α is a non-zero scalar function satisfies

$$\nabla_X \alpha = (X\alpha) = d\alpha(X) = \rho \eta(X) \tag{2.4}$$

 ρ being a certain scalar function given by $\rho = -(\xi \alpha)$. If we put

$$\phi X = \frac{1}{\alpha} \nabla_X \xi \,, \tag{2.5}$$

then from (2.3) and (2.5) we have

$$\phi X = X + \eta(X)\xi, \qquad (2.6)$$

from which it follows that ϕ is a symmetric (1,1) tensor and called the structure tensor of the manifold. Thus the Lorentzian manifold M^n together with the unit timelike concircular vector field ξ , its associated 1-form η and (1,1) tensor field ϕ is said to be a Lorentzian concircular structure manifold (briefly $(LCS)_n$ -manifold) ([1]). Especially, if we take $\alpha = 1$, then we can obtain the LP-Sasakian structure of Matsumoto ([4]). In a $(LCS)_n$ -manifold, the following relations hold ([1]):

a)
$$\eta(\xi) = -1$$
, b) $\phi \xi = 0$, (2.7)

c)
$$\eta(\phi X) = 0$$
, d) $g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y)$,

$$\eta(R(X,Y)Z) = (\alpha^2 - \rho)[g(Y,Z)\eta(X) - g(X,Z)\eta(Y)], \qquad (2.8)$$

$$S(X,\xi) = (n-1)(\alpha^2 - \rho)\eta(X),$$
 (2.9)

$$R(X,Y)\xi = (\alpha^2 - \rho)[\eta(Y)X - \eta(X)Y],$$
 (2.10)

$$(\nabla_X \phi)(Y) = \alpha \{ g(X, Y)\xi + 2\eta(X)\eta(Y)\xi + \eta(Y)X \}, \qquad (2.11)$$

$$(X\rho) = d\rho(X) = \beta\eta(X). \tag{2.12}$$

We now state and prove some curvature properties of $(LCS)_n$ -manifold which will be frequently used later on.

LEMMA 2.1. Let (M^n, g) be a $(LCS)_n$ -manifold. Then for any X, Y, Z the following relation holds:

$$R(X,Y)Z = \phi R(X,Y)Z + (\alpha^2 - \rho)\{g(Y,Z)\eta(X) - g(X,Z)\eta(Y)\}\xi \quad (2.13)$$

for any vector field X, Y, Z.

Proof. From
$$(2.3)$$
, (2.4) , (2.5) , (2.6) and (2.10) we can easily get (2.13) .

LEMMA 2.2. Let (M^n, g) be a $(LCS)_n$ -manifold. Then for any X, Y, Z the following relation holds:

$$(\nabla_W R)(X,Y)\xi = (2\alpha\rho - \beta)\{\eta(Y)\eta(W)X - \eta(X)\eta(W)Y\}$$

$$+ \alpha(\alpha^2 - \rho)\{g(Y,W)X - g(X,W)Y\} - \alpha R(X,Y)W.$$
(2.14)

Proof. By virtue of (2.3), (2.6) and (2.10) we can easily get (2.14).

LEMMA 2.3. Let (M^n, g) be a $(LCS)_n$ -manifold. Then for any X, Y, Z the following relation holds:

$$g((\nabla_W R)(X, Y)Z, U) = -g((\nabla_W R)(X, Y)U, Z). \tag{2.15}$$

Proof. By definition, we have

$$g((\nabla_W R)(X, Y)Z, U) = g(\nabla_W R(X, Y)Z, U) + \tilde{R}(X, Y, U, \nabla_W Z) + \tilde{R}(\nabla_W X, Y, U, Z) + \tilde{R}(X, \nabla_W Y, U, Z),$$
(2.16)

where $\tilde{R}(X,Y,Z,U) = g(R(X,Y)Z,U)$ and the property of curvature tensor have been used. Since ∇ is a metric connection, it follows that

$$g(\nabla_W R(X,Y)Z,U) = g(R(X,Y)\nabla_W U,Z) - \nabla_W g(R(X,Y)U,Z)$$
 (2.17)

and

$$\nabla_W g(R(X,Y)U,Z) = g(\nabla_W R(X,Y)U,Z) + g(R(X,Y)U,\nabla_W Z). \quad (2.18)$$

From (2.17) and (2.18) we have

$$g(\nabla_W R(X,Y)Z,U) = -g(\nabla_W R(X,Y)U,Z)$$

$$-g(R(X,Y)U,\nabla_W Z) + g(R(X,Y)\nabla_W U,Z).$$
(2.19)

Using (2.19) in (2.16), we get the relation (2.15).

3. Locally ϕ -recurrent $(LCS)_n$ -manifolds

DEFINITION 3.1. A $(LCS)_n$ -manifold (M^n, g) is said to be locally ϕ -recurrent if and only if there exists a non-zero 1-form A such that

$$\phi^2((\nabla_W R)(X, Y)Z) = A(W)R(X, Y)Z \tag{3.1}$$

holds for any vector field X, Y, Z, W orthogonal to ξ , that is, for any horizontal vector field X, Y, Z, W.

If, in particular, the 1-form A vanishes identically, then the manifold is said to be a locally ϕ -symmetric manifold ([5]).

THEOREM 3.1. A $(LCS)_n$ -manifold (M^n, g) is locally ϕ -recurrent if and only if the relation

$$(\nabla_W R)(X, Y)Z = \alpha(\alpha^2 - \rho)\{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\}\xi - \alpha g(R(X, Y)W, Z)\xi + A(W)R(X, Y)Z$$
(3.2)

holds for all horizontal vector fields X, Y, Z, W on M.

Proof. Let us consider a $(LCS)_n$ -manifold (M^n, g) which is locally ϕ -recurrent. Then using (2.6) in (3.1) we have

$$(\nabla_W R)(X, Y)Z + \eta((\nabla_W R)(X, Y)Z)\xi = A(W)R(X, Y)Z \tag{3.3}$$

for any X,Y,Z,W orthogonal to $\xi.$ In view of (2.15), it follows from (3.3) that

$$(\nabla_W R)(X, Y)Z = g((\nabla_W R)(X, Y)\xi, Z)\xi + A(W)R(X, Y)Z. \tag{3.4}$$

Using (2.14) in (3.4) we obtain the relation (3.2). Conversely, if in a $(LCS)_n$ -manifold the relation (3.2) holds, then applying ϕ on both sides of (3.2) and keeping in mind that X, Y, Z and W are orthogonal to ξ , we obtain (3.1). This proves the theorem.

THEOREM 3.2. A $(LCS)_n$ -manifold is of positive (resp. negative) constant curvature according as $\alpha^2 > \rho$ (resp. $\alpha^2 < \rho$) if and only if the relation

$$\phi^2((\nabla_W R)(X, Y)\xi) = A(W)R(X, Y)\xi \tag{3.5}$$

holds for all horizontal vector fields X, Y, W.

Proof. Using (2.6) in (3.5) we have

$$(\nabla_W R)(X, Y)\xi + \eta((\nabla_W R)(X, Y)\xi)\xi = A(W)R(X, Y)\xi. \tag{3.6}$$

In view of (2.14) and (2.10), (3.6) yields

$$(\nabla_W R)(X, Y)\xi = 0 \tag{3.7}$$

for any horizontal vector field X, Y, W. Also for any X, Y, W orthogonal to ξ , the relation (2.14) reduces to

$$(\nabla_W R)(X,Y)\xi = (2\alpha\rho - \beta)\{\eta(Y)\eta(W)X - \eta(X)\eta(W)Y\}$$

$$+ \alpha(\alpha^2 - \rho)\{g(Y,W)X - g(X,W)Y\} - \alpha R(X,Y)W.$$
(3.8)

From (3.7) and (3.8), it follows that

$$R(X,Y)W = (\alpha^2 - \rho)\{g(Y,W)X - g(X,W)Y\}$$
(3.9)

for any horizontal vector field X, Y, W. We shall now show that $\alpha^2 - \rho$ is constant. Taking covariant derivative along any horizontal vector field X and then using (2.4) and (2.12) we obtain

$$\nabla_X(\alpha^2 - \rho) = 0$$

and hence $\alpha^2 - \rho = \text{constant}$. Thus the manifold is of constant curvature.

Conversely, if a $(LCS)_n$ -manifold is of constant curvature, then from (3.9) it follows that the relation (3.5) holds. This proves the theorem.

THEOREM 3.3. In a locally ϕ -recurrent $(LCS)_n$ -manifold (M^n, g) (n > 3), $\frac{r}{2}$ is an eigenvalue of the Ricci tensor corresponding to the eigenvector ρ , where ρ is the associated vector field of the 1-form A.

Proof. In a locally ϕ -recurrent $(LCS)_n$ -manifold the relation (3.1) holds. Changing W, X, Y cyclically in (3.1) and then adding the results we obtain

$$\begin{split} & \left[(\nabla_W R)(X,Y)Z + (\nabla_X R)(Y,W)Z + (\nabla_Y R)(W,X)Z \right] \\ & + \left[\eta((\nabla_W R)(X,Y)Z) + \eta((\nabla_X R)(Y,W)Z) + \eta((\nabla_Y R)(W,X)Z) \right] \xi \\ & = A(W)R(X,Y)Z + A(X)R(Y,W)Z + A(Y)R(W,X)Z \,, \end{split}$$

which yields by virtue of Bianchi identity that

$$A(W)R(X,Y)Z + A(X)R(Y,W)Z + A(Y)R(W,X)Z = 0$$
(3.10)

for all X, Y, Z, W orthogonal to ξ . Taking an inner product on both sides of (3.10) by any horizontal vector field U, we get

$$A(W)g(R(X,Y)Z,U) + A(X)g(R(Y,W)Z,U) + A(Y)g(R(W,X)Z,U) = 0.$$
(3.11)

Contraction over X and U in (3.11) yields

$$A(W)S(Y,Z) + A(R(Y,W)Z) - A(Y)S(W,Z) = 0.$$
(3.12)

Again, contracting X and U in (3.12) we obtain

$$S(W, \rho) = \frac{r}{2} A(W) = \frac{r}{2} g(W, \rho).$$

This proves the theorem. ■

THEOREM 3.4. In a locally ϕ -recurrent $(LCS)_n$ -manifold (M^n, g) , the 1-form of recurrence A is given by

$$A(W) = \frac{\mathrm{d}r(W)}{r} \tag{3.13}$$

for all W orthogonal to ξ , where r is the non-zero and non-constant scalar curvature of the manifold.

Proof. In a locally ϕ -recurrent $(LCS)_n$ -manifold, the relation (3.2) holds good. Taking an inner product on both sides of (3.2) by an arbitrary horizontal vector field U tangent to M, we obtain

$$g((\nabla_W R)(X, Y)Z, U) = A(W)g(R(X, Y)Z, U). \tag{3.14}$$

Contracting over X and U in (3.14), we get

$$(\nabla_W S)(Y, Z) = A(W)S(Y, Z) \tag{3.15}$$

which yields again by contraction over Y and Z, the relation (3.13). This proves the theorem. \blacksquare

In particular, if r is a non-zero constant in the direction orthogonal to ξ , then the locally ϕ -recurrent $(LCS)_n$ -manifold reduces to the locally ϕ -symmetric $(LCS)_n$ -manifold. Thus we have the following corollary:

COROLLARY 3.1. If in a locally ϕ -recurrent $(LCS)_n$ -manifold (M^n, g) the scalar curvature is a non-zero constant along the orthogonal direction to ξ , then the manifold is locally ϕ -symmetric.

We shall now construct several examples of locally ϕ -recurrent $(LCS)_n$ manifolds.

Example 3.1. We consider a 3-dimensional manifold

$$M = \{(x, y, z) \in \mathbb{R}^3 : x \neq \pm \sqrt{2}z^2, \ x \neq 0, \ z \neq 0\},$$

where (x, y, z) are the standard coordinates in \mathbb{R}^3 . Let $\{E_1, E_2, E_3\}$ be linearly independent global frame on M given by

$$E_1 = z \frac{\partial}{\partial x}, \qquad E_2 = zx \frac{\partial}{\partial y}, \qquad E_3 = \frac{\partial}{\partial z}.$$

Let g be the Lorentzian metric defined by

$$g(E_1, E_3) = g(E_2, E_3) = g(E_1, E_2) = 0,$$

 $g(E_1, E_1) = g(E_2, E_2) = 1,$
 $g(E_3, E_3) = -1.$

Let η be the 1-form defined by $\eta(U) = g(U, E_3)$ for any $U \in \chi(M)$. Let ϕ be the (1,1) tensor field defined by $\phi E_1 = E_1$, $\phi E_2 = E_2$, $\phi E_3 = 0$. Then using the linearity of ϕ and g we have

$$\eta(E_3) = -1,$$

$$\phi U = U + \eta(U)E_3,$$

$$g(\phi U, \phi W) = g(U, W) + \eta(U)\eta(W)$$

for any $U, W \in \chi(M)$.

Let ∇ be the Levi-Civita connection with respect to the Lorentzian metric g and R be the curvature tensor of g. Then we have

$$[E_1, E_2] = \frac{z}{x} E_2, \qquad [E_1, E_3] = -\frac{1}{z} E_1, \qquad [E_2, E_3] = -\frac{1}{z} E_2.$$
 (3.16)

Taking $E_3 = \xi$ and using Koszul formula for the Lorentzian metric g, we can easily calculate

$$\nabla_{E_1} E_3 = -\frac{1}{z} E_1 , \qquad \nabla_{E_1} E_1 = -\frac{1}{z} E_3 , \qquad \nabla_{E_1} E_2 = 0 ,$$

$$\nabla_{E_2} E_3 = -\frac{1}{z} E_2 , \qquad \nabla_{E_3} E_2 = 0 , \qquad \nabla_{E_2} E_1 = -\frac{z}{x} E_2 ,$$

$$\nabla_{E_3} E_3 = 0 , \qquad \nabla_{E_2} E_2 = \frac{z}{x} E_1 - \frac{1}{z} E_3 , \qquad \nabla_{E_3} E_1 = 0 .$$

From the above it can be easily seen that $E_3 = \xi$ is a unit timelike concircular vector field and hence (ϕ, ξ, η, g) is a $(LCS)_3$ structure on M. Consequently $M^3(\phi, \xi, \eta, g)$ is a $(LCS)_3$ -manifold with $\alpha = -\frac{1}{z} \neq 0$ such that $(X\alpha) = \rho \eta(X)$ where $\rho = -\frac{1}{z^2}$. Using the above relations, we can easily calculate the non-vanishing components of the curvature tensor R as follows:

$$R(E_{2}, E_{3})E_{3} = -\frac{2}{z^{2}}E_{2}, \qquad R(E_{1}, E_{3})E_{3} = -\frac{2}{z^{2}}E_{1},$$

$$R(E_{1}, E_{2})E_{2} = -\left[2\left(\frac{z}{x}\right)^{2} - \frac{1}{z^{2}}\right]E_{1}, \qquad R(E_{2}, E_{3})E_{2} = -\frac{2}{z^{2}}E_{3},$$

$$R(E_{1}, E_{3})E_{1} = -\frac{2}{z^{2}}E_{3}, \qquad R(E_{1}, E_{2})E_{1} = \left[2\left(\frac{z}{x}\right)^{2} - \frac{1}{z^{2}}\right]E_{2}$$

and the components which can be obtained from these by the symmetry properties. From the above, we can easily calculate the non-vanishing components of the Ricci tensor S as follows:

$$S(E_1, E_1) = -\left[2\left(\frac{z}{x}\right)^2 - \frac{1}{z^2}\right],$$

$$S(E_2, E_2) = -\left[2\left(\frac{z}{x}\right)^2 - \frac{1}{z^2}\right],$$

$$S(E_3, E_3) = -\frac{4}{z^2}.$$

Hence the scalar curvature r is given by

$$r = \sum_{i=1}^{3} \epsilon_i S(E_i, E_i) = -\left[4\left(\frac{z}{x}\right)^2 - \frac{2}{z^2}\right] \neq 0,$$

where $\epsilon_i = g(E_i, E_i)$.

Consequently, $dr(E_1) = -8(\frac{z}{x})^3 \neq 0$ but $dr(E_2) = 0$. We shall show that the manifold (M^3, g) under consideration is locally ϕ -recurrent $(LCS)_3$ -manifold. To verify this we calculate the covariant derivatives of the required non-zero components of the curvature tensor as follows:

$$(\nabla_{E_1} R)(E_1, E_2)E_1 = -4\left(\frac{z}{x}\right)^3 E_2,$$

$$(\nabla_{E_1} R)(E_1, E_2)E_2 = 4\left(\frac{z}{x}\right)^3 E_1,$$

$$(\nabla_{E_2} R)(E_1, E_2)E_1 = \left[\left(\frac{1}{z}\right)^3 - \frac{2z}{x^2}\right] E_3.$$

This implies that the manifold under consideration is not locally ϕ -symmetric. Let us now consider the components of the 1-form A as follows:

$$A(E_i) = \begin{cases} -\frac{4z^5}{x(2z^4 - x^2)} & \text{for } i = 1, \\ 0 & \text{otherwise}, \end{cases}$$

at any point $x \in M$. In our M^3 , (3.1) reduces with the 1-form to the following equations:

$$\phi^2((\nabla_{E_i}R)(E_j, E_k)E_l = A(E_i)R(E_j, E_k)E_l,$$

for i, j, k, l = 1, 2. Hence the manifold under consideration satisfies the following relation

$$\phi^2((\nabla_W R)(X, Y)Z) = A(W)R(X, Y)Z$$

for all vector fields X, Y, Z, W orthogonal to ξ , that is, for any horizontal vector field X, Y, Z, W. Thus the manifold (M^3, g) under consideration is neither locally symmetric nor locally ϕ -symmetric but locally ϕ -recurrent $(LCS)_3$ -manifold. Hence we can state the following:

THEOREM 3.5. There exists a locally ϕ -recurrent $(LCS)_3$ -manifold which is neither locally symmetric nor locally ϕ -symmetric.

EXAMPLE 3.2. We consider the 4-dimensional manifold

$$M = \left\{ (x, y, z, u) \in \mathbb{R}^4 \, : \, u \neq 0, \, \, x \neq \pm 1, \pm \sqrt{2} \, \right\},$$

where (x, y, z, u) are the standard coordinates in \mathbb{R}^4 . Let $\{E_1, E_2, E_3, E_4\}$ be linearly independent global frame on M given by

$$E_1 = -\frac{1}{u}\frac{\partial}{\partial x}, \quad E_2 = -\frac{x}{u}\left(\frac{\partial}{\partial y} + \frac{\partial}{\partial z}\right), \quad E_3 = -\frac{1}{u}\frac{\partial}{\partial z}, \quad E_4 = \frac{\partial}{\partial u}.$$

Let g be the Lorentzian metric defined by

$$g(E_1, E_1) = g(E_2, E_2) = g(E_3, E_3) = 1,$$

 $g(E_4, E_4) = -1,$
 $g(E_i, E_j) = 0$ for $i \neq j$.

Let η be the 1-form defined by $\eta(U) = g(U, E_4)$ for any $U \in \chi(M)$. Let ϕ be the (1,1) tensor field defined by $\phi E_1 = E_1$, $\phi E_2 = E_2$, $\phi E_3 = E_3$ and $\phi E_4 = 0$. Then using the linearity of ϕ and g we have

$$\eta(E_4) = -1,$$

$$\phi^2 U = U + \eta(U)E_4,$$

$$g(\phi U, \phi W) = g(U, W) + \eta(U)\eta(W)$$

for any $U, W \in \chi(M)$. Let ∇ be the Levi-Civita connection with respect to the Lorentzian metric g and R be the curvature tensor of g. Then we have

$$[E_1, E_4] = -\frac{1}{u} E_1,$$
 $[E_1, E_2] = -\frac{1}{xu} E_2,$ $[E_2, E_4] = -\frac{1}{u} E_2,$ $[E_3, E_4] = -\frac{1}{u} E_3.$

Taking $E_4 = \xi$ and using Koszul formula for the Lorentzian metric g, we can easily calculate

$$\nabla_{E_1} E_4 = -\frac{1}{u} E_1, \qquad \nabla_{E_2} E_4 = -\frac{1}{u} E_2, \qquad \nabla_{E_3} E_4 = -\frac{1}{u} E_3,$$

$$\nabla_{E_1} E_1 = -\frac{1}{u} E_4, \qquad \nabla_{E_2} E_1 = \frac{1}{xu} E_2, \qquad \nabla_{E_3} E_3 = -\frac{1}{u} E_4,$$

$$\nabla_{E_2} E_2 = -\frac{1}{u} E_4 - \frac{1}{ux} E_1.$$

From the above it can be easily seen that $E_4 = \xi$ is a unit timelike concircular vector field and hence (ϕ, ξ, η, g) is a $(LCS)_4$ structure on M. Consequently $M^4(\phi, \xi, \eta, g)$ is a $(LCS)_4$ -manifold with $\alpha = -\frac{1}{u} \neq 0$ and $\rho = -\frac{1}{u^2}$. Using the above relations, we can easily calculate the non-vanishing components of the curvature tensor as follows:

$$R(E_2, E_3)E_2 = -\frac{1}{u^2}E_3$$
, $R(E_2, E_3)E_3 = \frac{1}{u^2}E_2$,
 $R(E_1, E_3)E_1 = -\frac{1}{u^2}E_3$, $R(E_1, E_3)E_3 = \frac{1}{u^2}E_1$,
 $R(E_3, E_4)E_4 = -\frac{2}{u^2}E_3$, $R(E_3, E_4)E_3 = -\frac{2}{u^2}E_4$,

$$R(E_1, E_4)E_1 = -\frac{2}{u^2}E_4, \qquad R(E_1, E_4)E_4 = -\frac{2}{u^2}E_1,$$

$$R(E_2, E_4)E_2 = -\frac{2}{u^2}E_4, \qquad R(E_2, E_4)E_4 = -\frac{2}{u^2}E_2,$$

$$R(E_1, E_2)E_2 = \frac{1}{u^2}\left(1 - \frac{2}{x^2}\right)E_1, \qquad R(E_1, E_2)E_1 = -\frac{1}{u^2}\left(1 - \frac{2}{x^2}\right)E_2,$$

and the components which can be obtained from these by the symmetry properties. From the above, we can easily calculate the scalar curvature r as follows:

$$r = \sum_{i=1}^{4} \epsilon_i S(E_i, E_i) = \frac{2}{u^2} \left(1 - \frac{2}{x^2} \right) \neq 0,$$

where $\epsilon_i = g(E_i, E_i)$. Consequently, $dr(E_1) = -\frac{8}{(ux)^3} \neq 0$, but $dr(E_2) = 0$, $dr(E_3) = 0$. We shall now show that the manifold (M^4, g) is locally ϕ -recurrent $(LCS)_4$ -manifold. To verify this we calculate the covariant derivatives of the required non-zero components of the curvature tensor as follows:

$$(\nabla_{E_1}R)(E_1, E_2)E_1 = \frac{4}{(ux)^3}E_2,$$

$$(\nabla_{E_1}R)(E_1, E_2)E_2 = -\frac{4}{(ux)^3}E_1 + \left(\frac{1}{u^3} + \frac{1}{x^2u^3}\right)E_4,$$

$$(\nabla_{E_2}R)(E_1, E_2)E_1 = -\frac{2}{x^2u^3}E_4.$$

This implies that the manifold under consideration is not locally ϕ -symmetric. Let us now consider the components of the 1-form as follows:

$$A(E_i) = \begin{cases} -\frac{2}{ux(x^2 - 1)} & \text{for } i = 1, \\ 0 & \text{otherwise,} \end{cases}$$

at any point $x \in M$. In our M^3 , (3.1) reduces with the 1-form to the following equations:

$$\phi^2((\nabla_{E_i}R)(E_j, E_k)E_l) = A(E_i)R(E_j, E_k)E_l,$$

for i, j, k, l = 1, 2. Hence the manifold satisfies the following relation

$$\phi^2((\nabla_W R)(X, Y)Z) = A(W)R(X, Y)Z$$

for all vector fields X, Y, Z, W orthogonal to ξ . Thus the manifold (M^4, g) under consideration is neither locally symmetric nor locally ϕ -symmetric but locally ϕ -recurrent $(LCS)_4$ -manifold. Hence we can state the following:

THEOREM 3.6. There exists a locally ϕ -recurrent $(LCS)_4$ -manifold which is neither locally symmetric nor locally ϕ -symmetric.

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